OATSCON23

Rethinking Connectivity in Agriculture

an Avena use case

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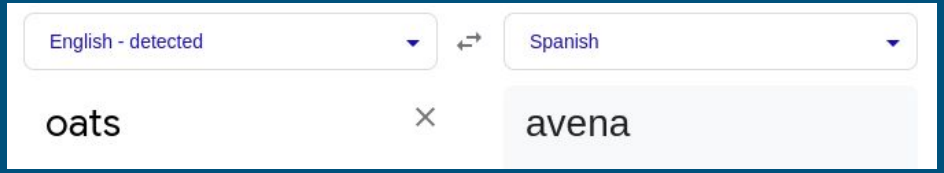
OATS

IoT4Ag

PURDUE UNIVERSITY

What is Avena?



Avena is an *open source*

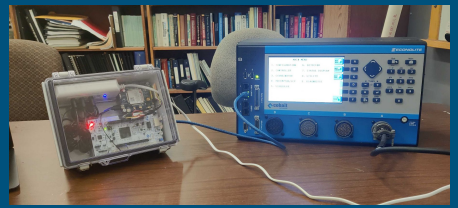
software and *communication* stack

It's not intended as a commercial product
(but could be used in one)

Our goal: architecture research and disruption

We eat our own dog food:

- ISOBlue
- Purdue OATS DataStation (POD)
- Data Diode (connectivity)
- … *future edge computing research* …



Avena design goal

Create opportunity.

Borrowing ideas: Be a matchmaker

Android is an **open source software stack** created for a wide array of devices with different form factors. Android's primary purpose is to create an **open software platform available for carriers, OEMs, and developers to make their innovative ideas a reality** and to introduce a successful, real-world product that improves the mobile experience for users.

Android is designed so that there's **no central point of failure, where one industry player restricts or controls the innovations of another.** The result is a full, production-quality consumer product with source code open for customization and porting.

https://source.android.com/docs/setup/about

Borrowing ideas: Be the matchmaker

Android abstracts *hardware vendors* from *software vendors* via a standard API.

Android's pre-competitive interface enables a much larger market than one of the vendors could create alone.

Consider: *What happened to Windows phones? Blackberry? Tizen?*

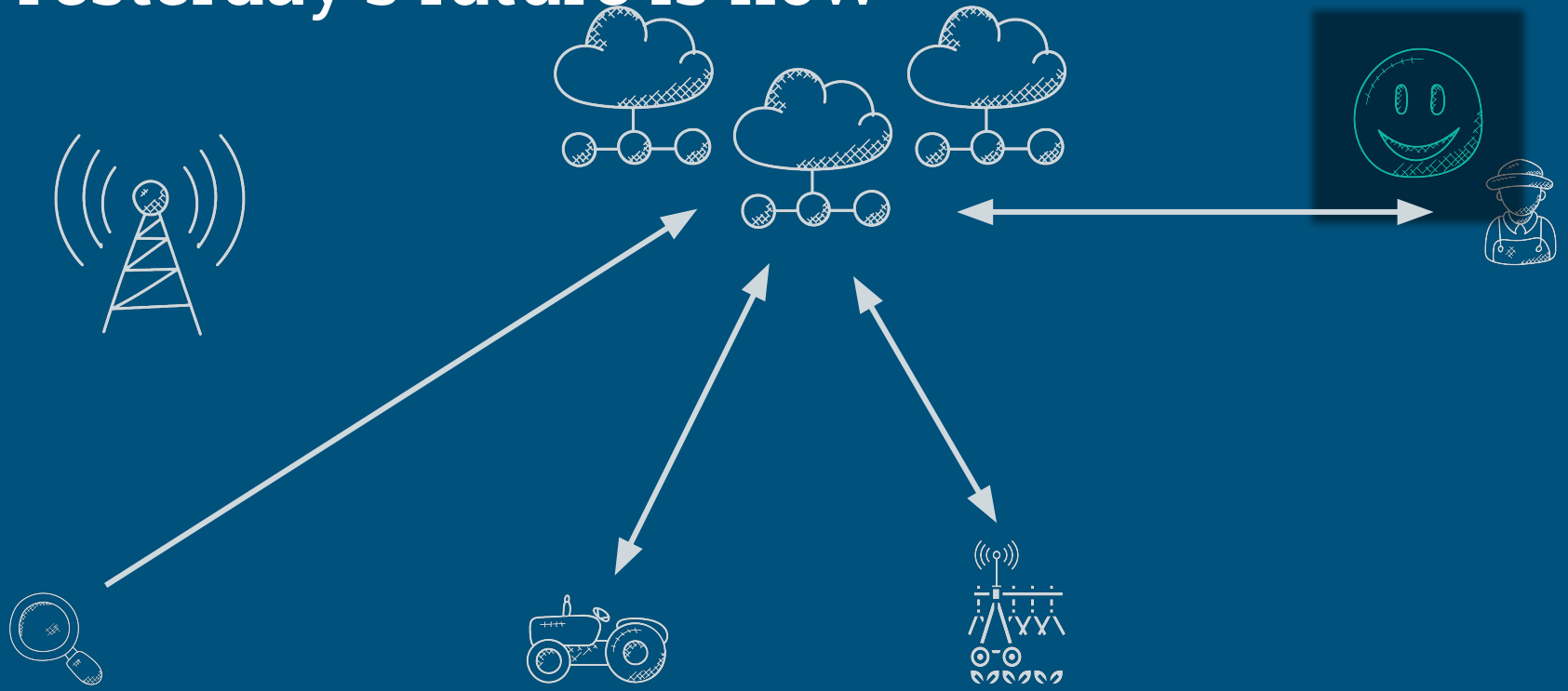
Why not just use Android?
Android focus on devices. Avena focuses on a full system of things (including Android things).

Already partly there?
Avena on a Deere MTG?

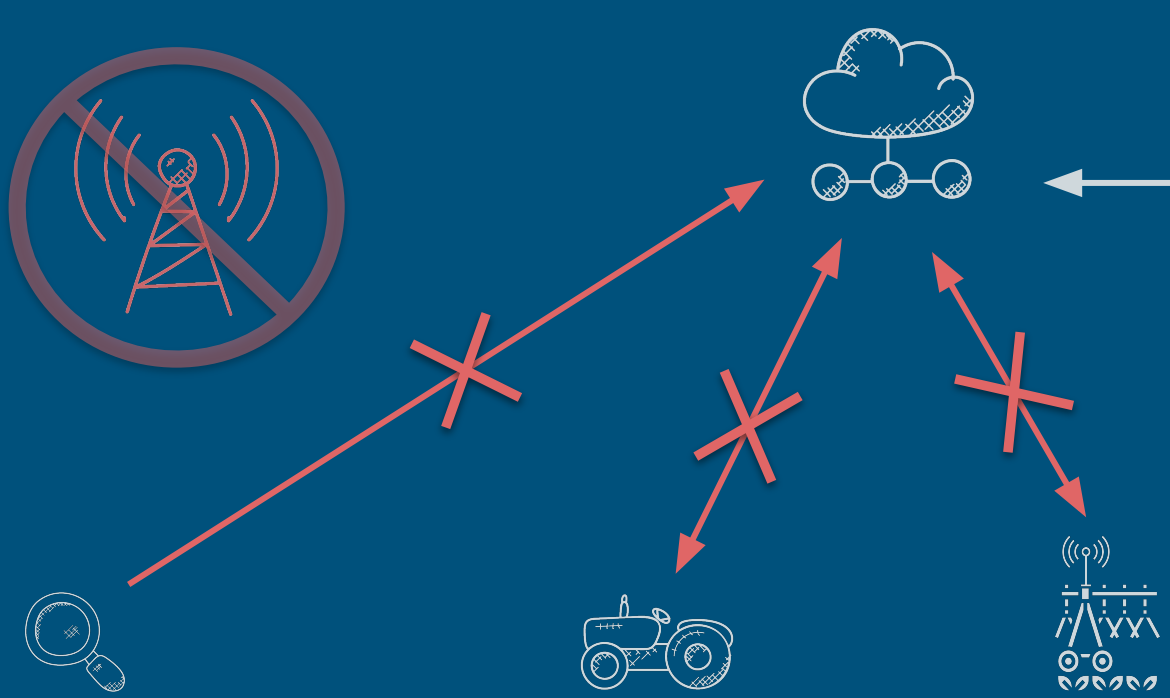
Avena design goal

Build software local first.

Yesterday's future is now



...except when it isn't



Things can't just stop because the network goes away!

In agriculture,
network outage is not *exceptional*,
it is ***typical***.

Aside: NATS

NATS is an open source project that passes messages between a set of publishers and subscribers

Publishers and subscribers don't know about each other

Subjects

PUBLISH j1939.pto

```
{ time: 15, speed: 1200, units: RPM }
```

PUBLISH j1939.pos

```
{ time: 15, speed: 4, lat: 40.41, lon: -86.8 }
```

PUBLISH gps.pos

```
{ time: 15, speed: 4, lat: 40.4, lon: -86.9 }
```

Message

NATS

SUBSCRIBE gps.pos

SUBSCRIBE *.pos

SUBSCRIBE j1939.pto

Action

Aside: NATS

Publish and subscribe

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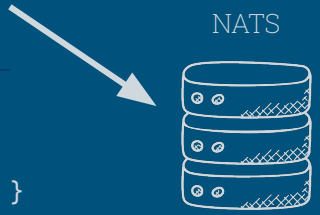

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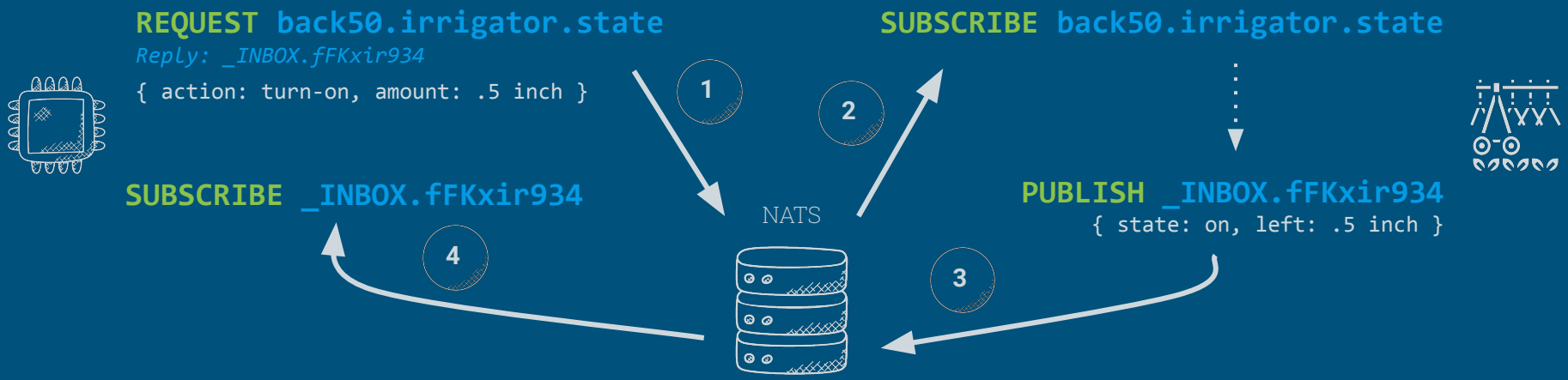
Aside: NATS

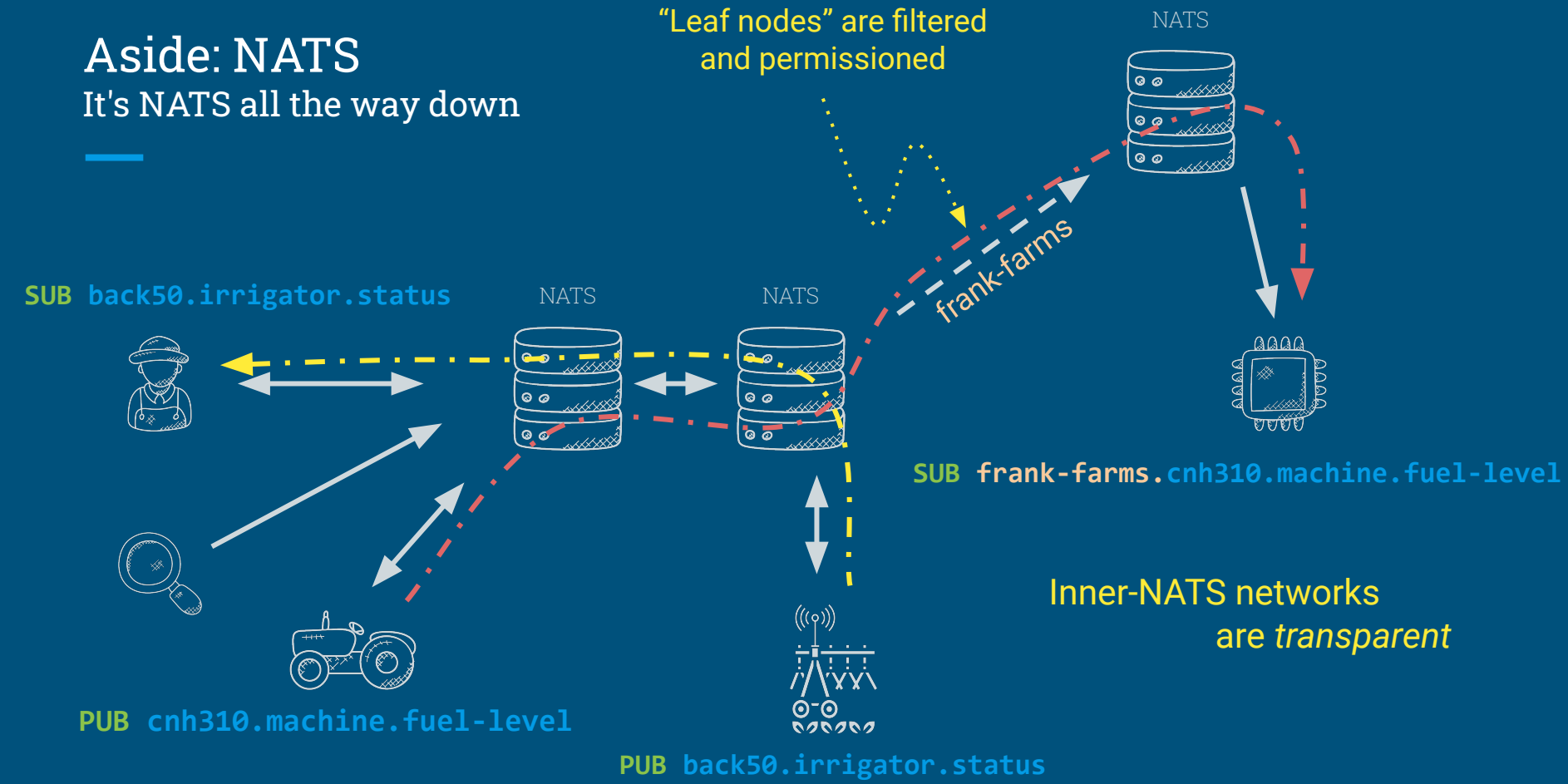
Request + Reply

Also known as a Remote Procedure Call (RPC)
or
Command and Control



Aside: NATS

It's NATS all the way down

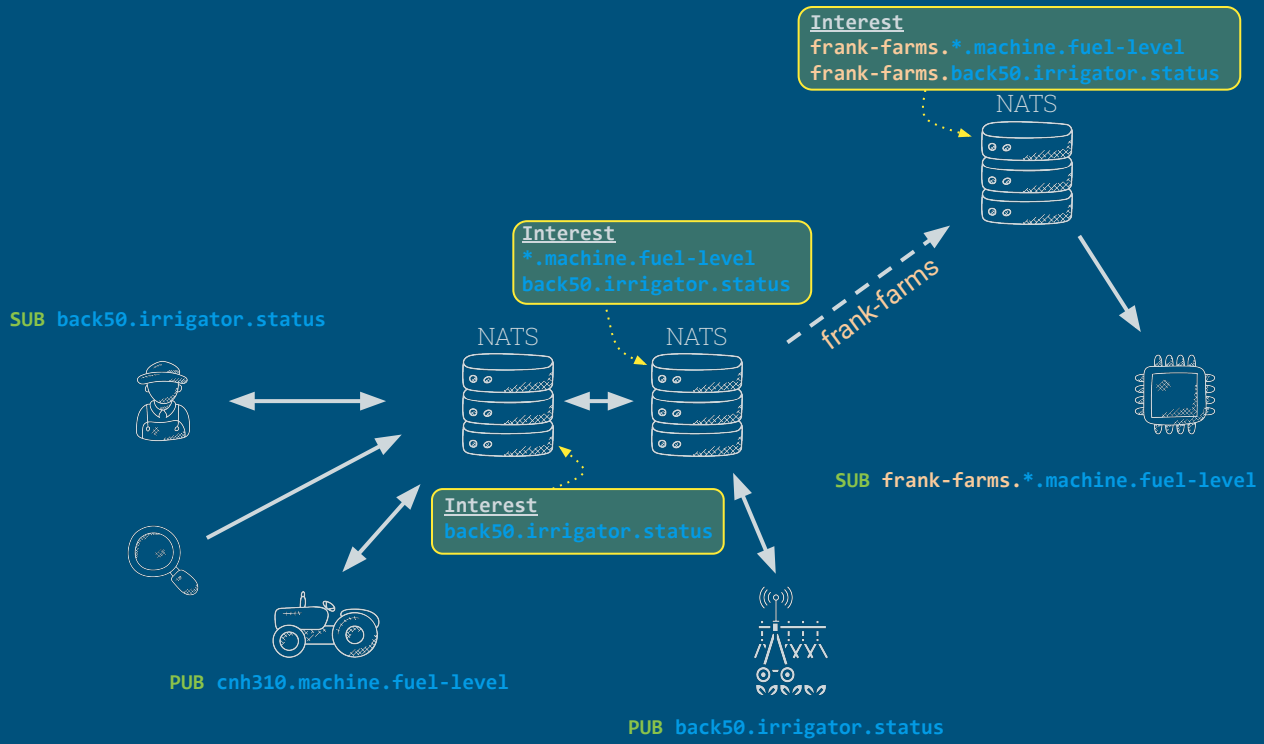


Aside: NATS
Interest graphs

Services receive data by “demanding” it through a subscription pattern.

The cumulative interest in subjects is communicated to peer NATS servers.

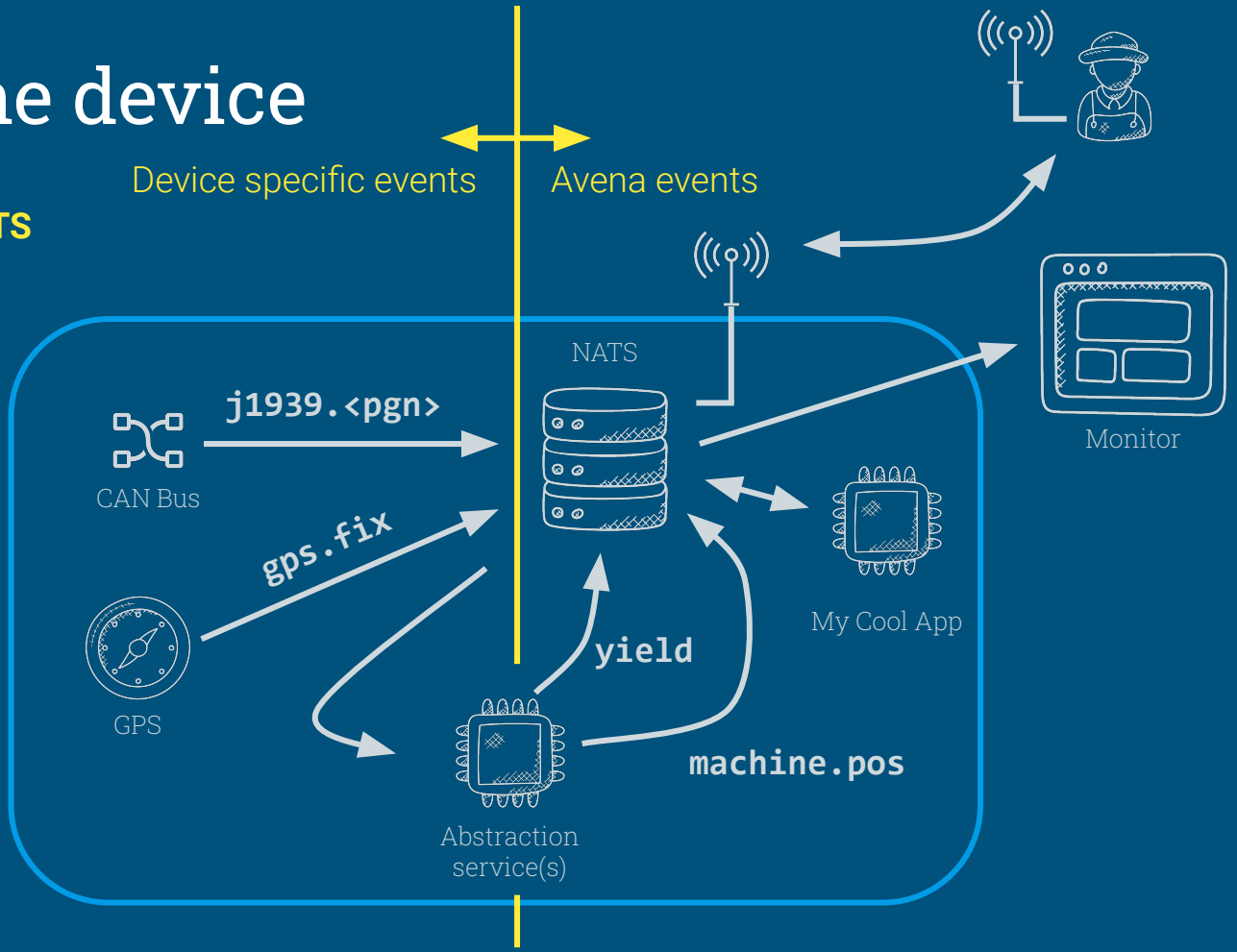
NATS *only* sends messages to peers that have interest in the data



Avena on the device

Avena devices have computing and a **local NATS**

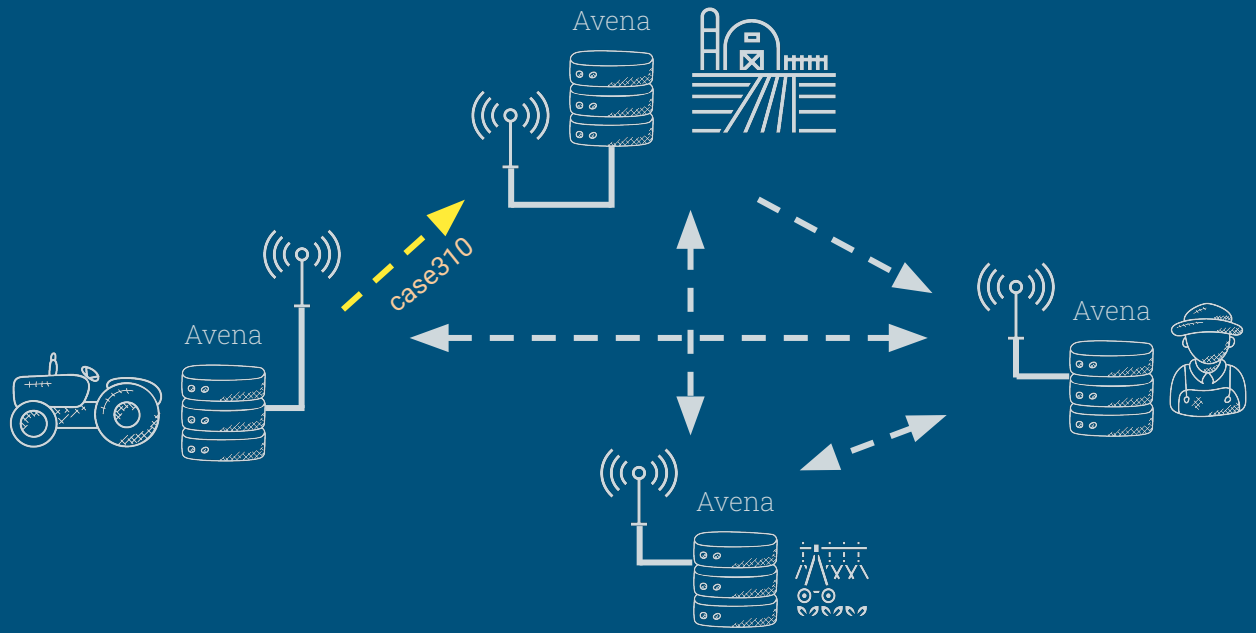
Function is *not dependent* upon external connectivity



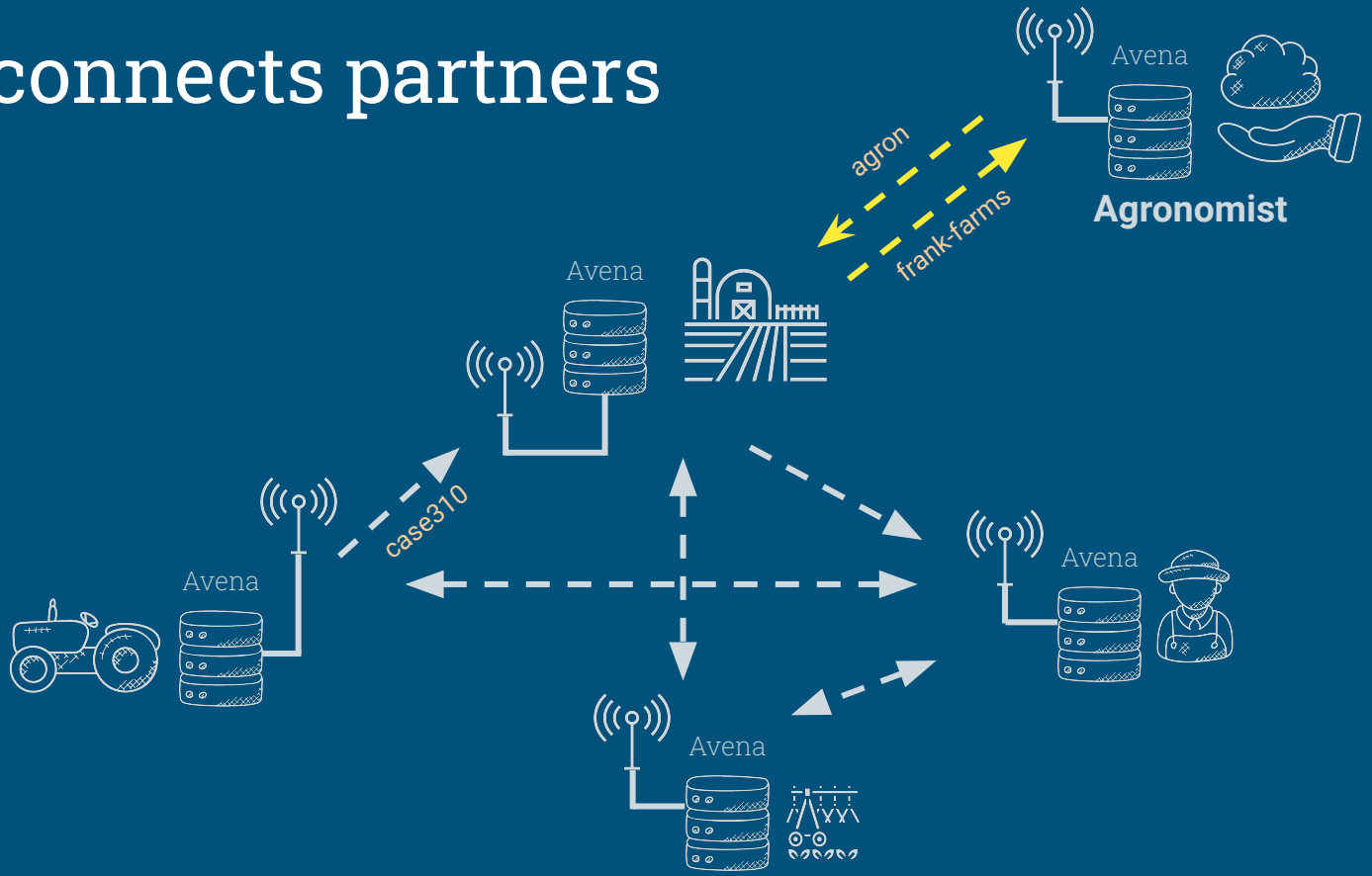
Avena design goal

Connect the things.

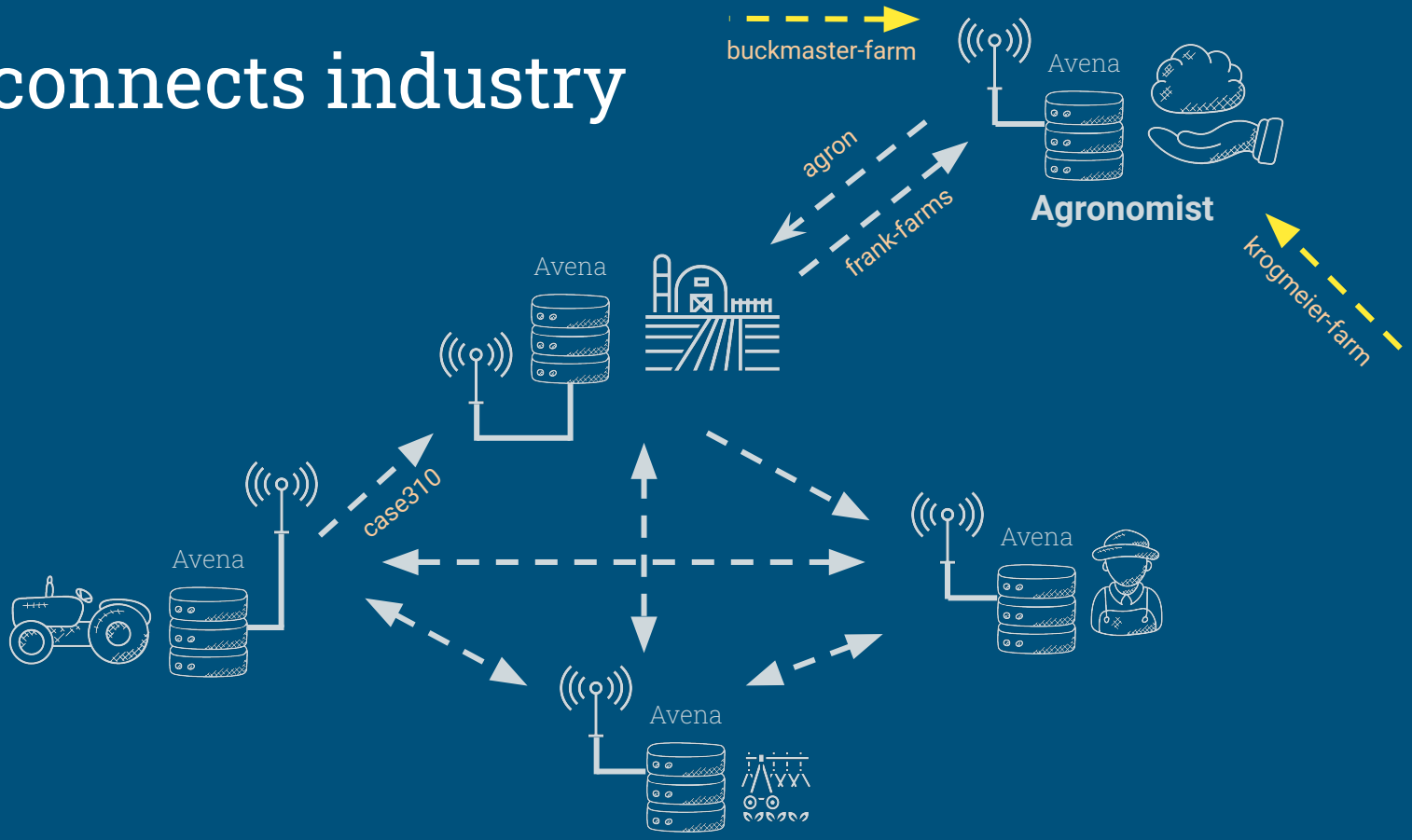
Avena connects the farm



Avena connects partners



Avena connects industry



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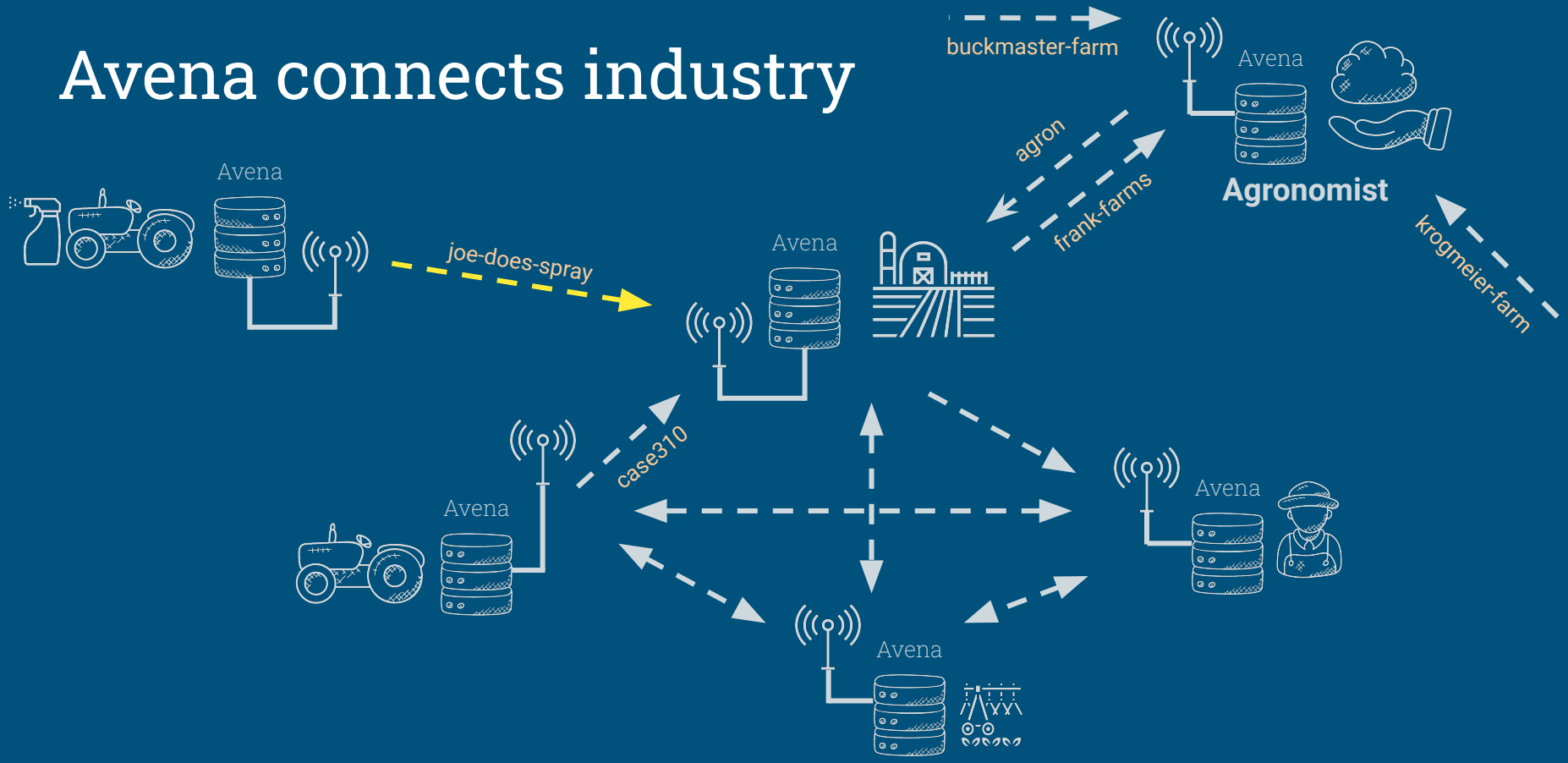


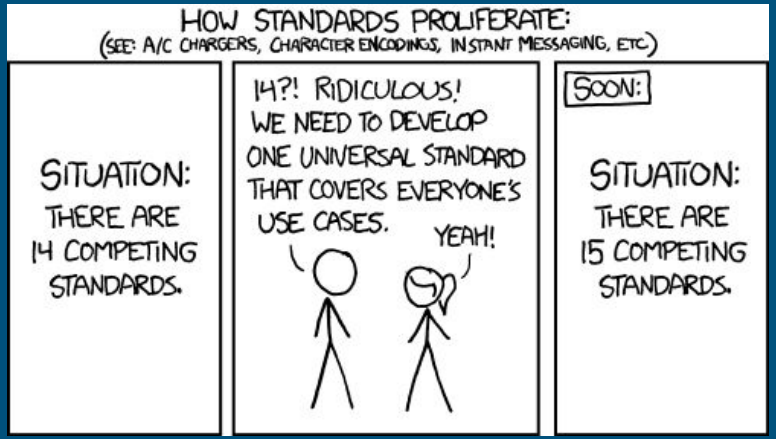
Avena design goal

Interoperability is message passing.

(and also how one solves distributed system)

Messages are the data.

Based on leading distributed system design patterns,
we lean on sharing messages, not *data files*.



Data files should be created by the *consumer,* however best *fits their needs*.

It is more than NATS

NATS provides many positive benefits and is an excellent base, but

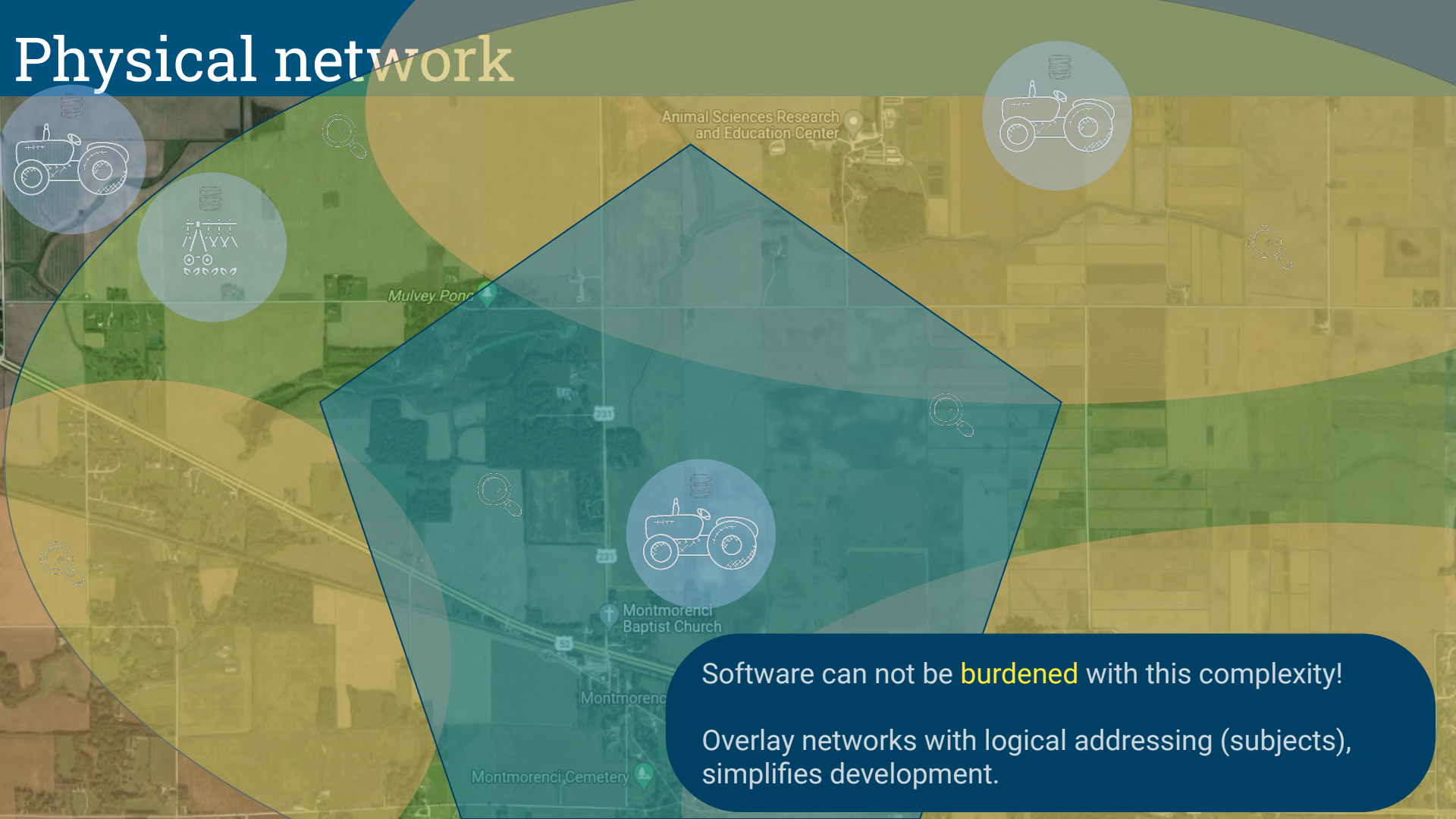
Avena events…

- Need standardized schemas
- Need standardized subjects
- Need distributed tolerant timestamps (global order)
- Must be secure and allow for (distributed + disconnected) permissions
- Opportunistically move messages even when connections are unstable
- Services must be discoverable
- Etc.

Avena design goal

Software doesn't know about the physical network

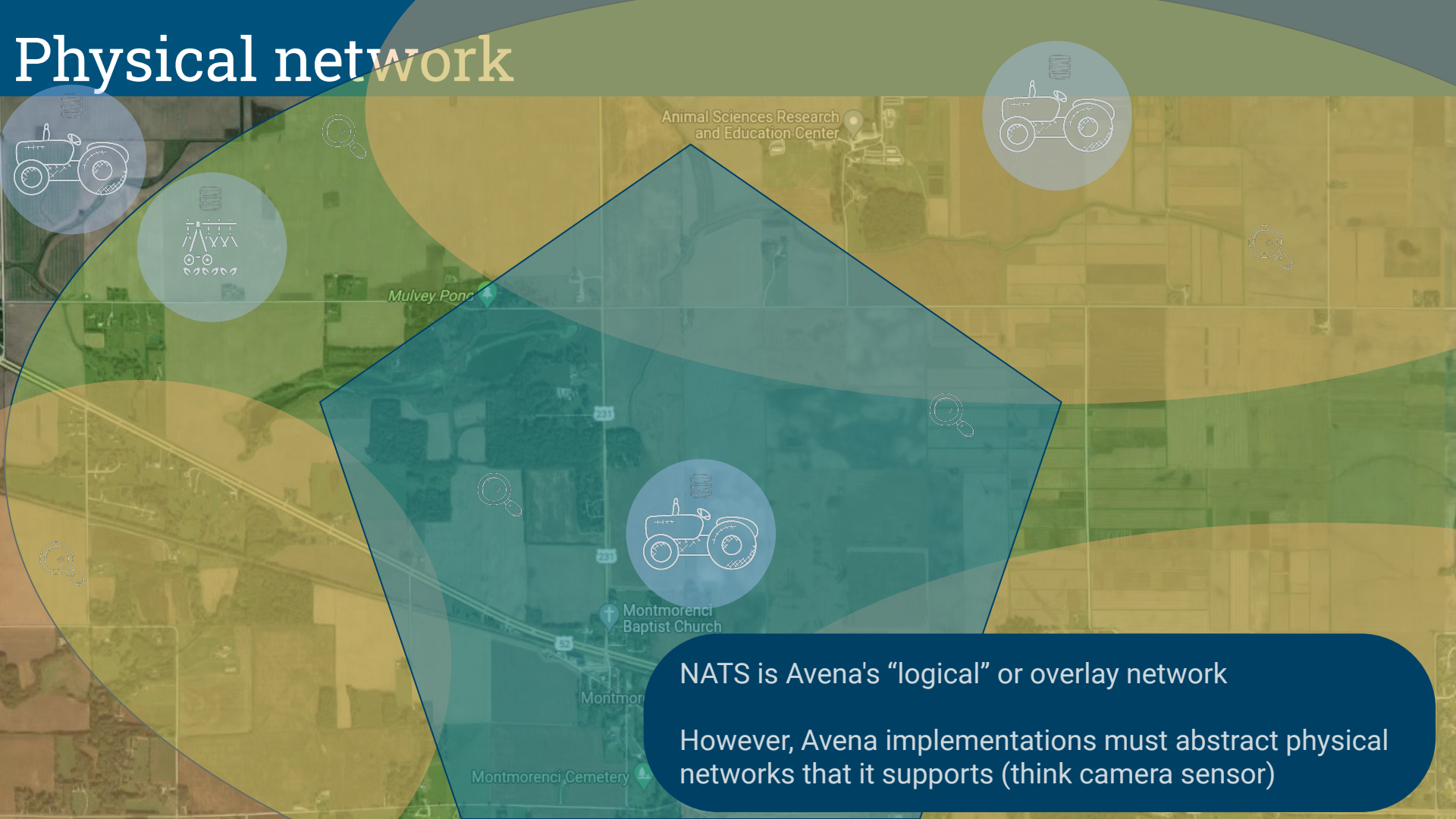
Physical network



Software can not be burdened with this complexity!

Overlay networks with logical addressing (subjects), simplifies development.

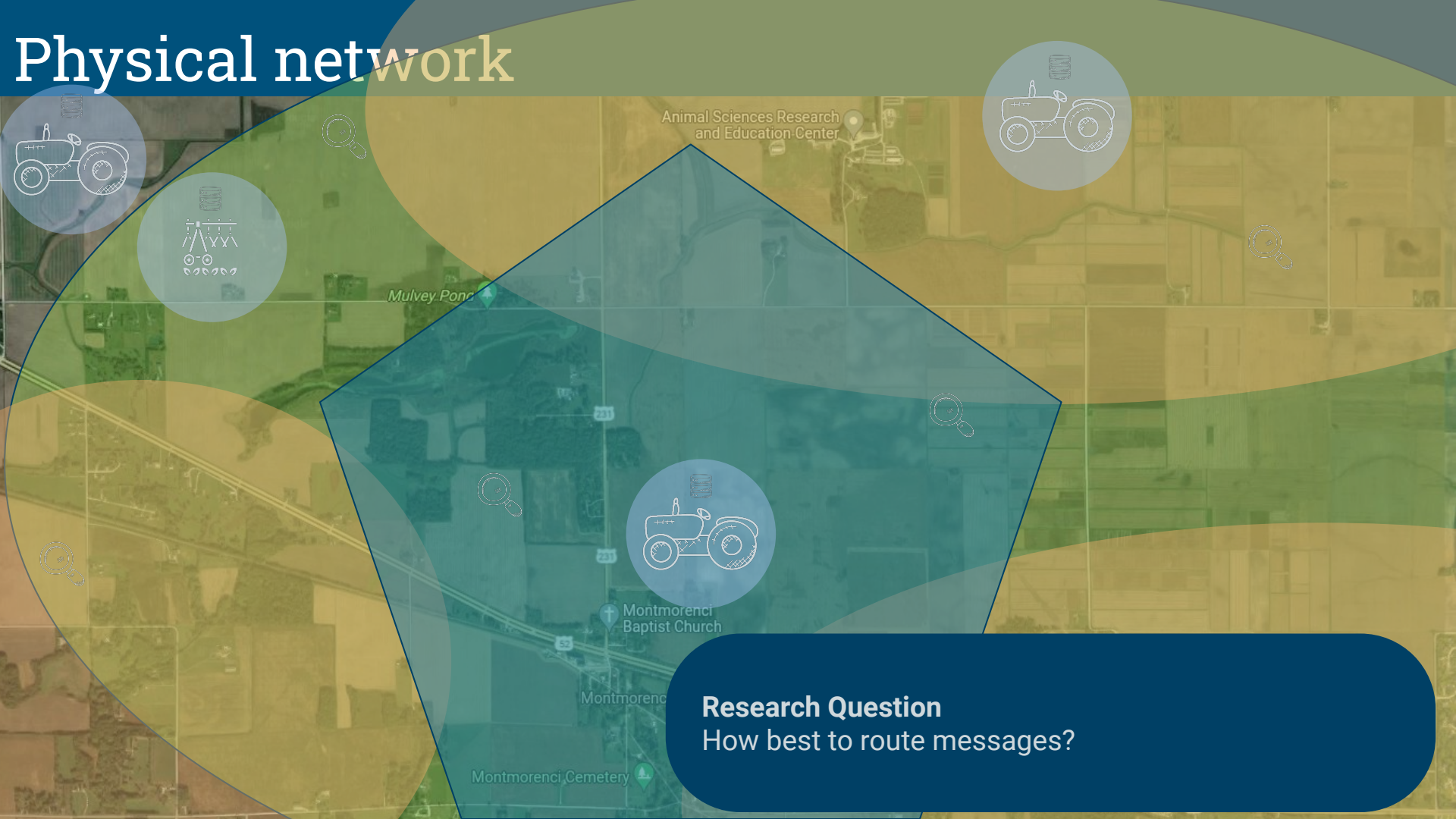
Physical network



NATS is Avena's “logical” or overlay network

However, Avena implementations must abstract physical networks that it supports (think camera sensor)

Physical network



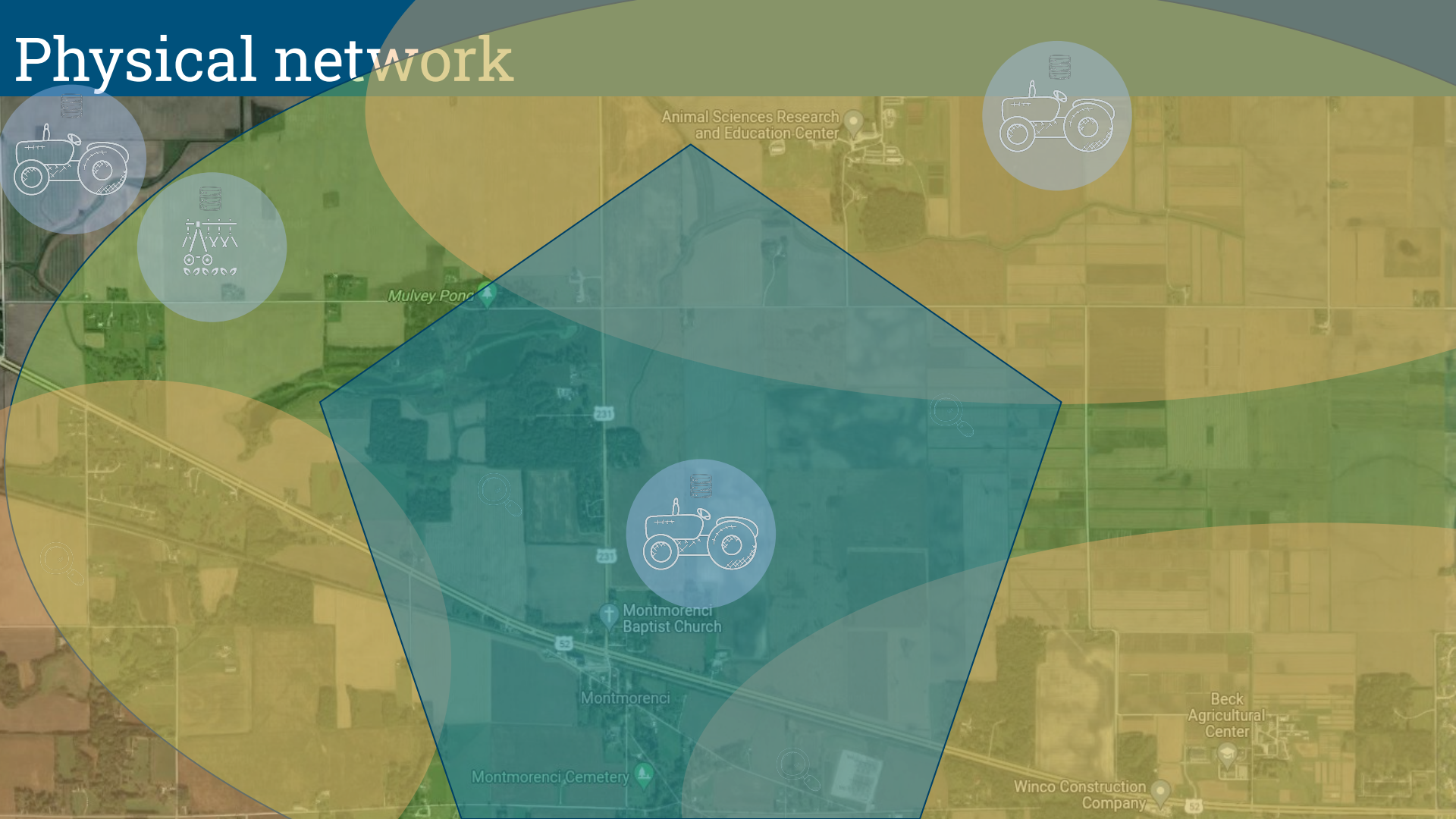
Research Question
How best to route messages?

Avena design goal (we think?)

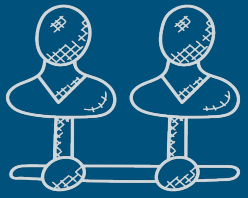
Ag networks should be opportunistic.

"Delay tolerant"

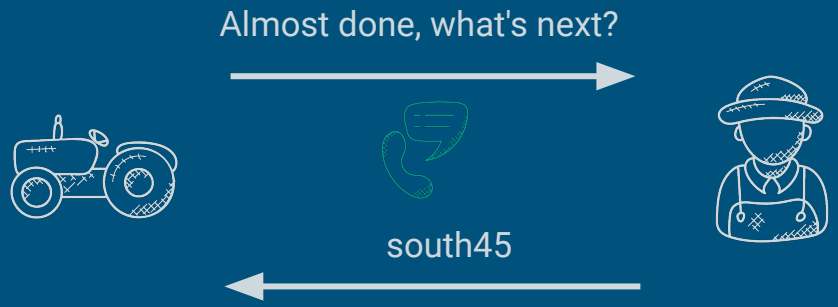
Physical network



We're already doing it!



HumanNet



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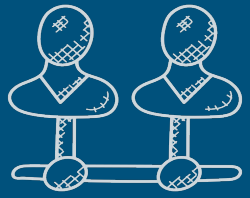
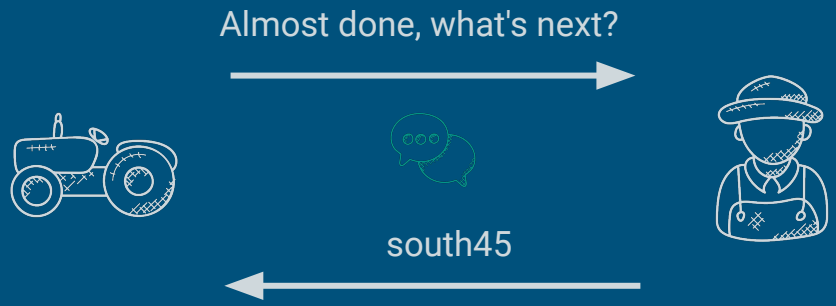


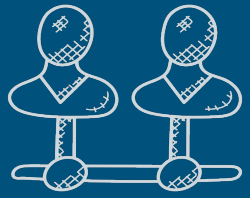
HumanNet

Scenario: What if voice calls won't go through?



Opportunistically select text message network

We're already doing it!

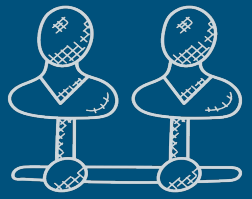


HumanNet

Scenario: What if no cell at all?

Physically move message to the field, and use the "local voice" network

We're already doing it!



HumanNet

Scenario: What if voice calls won't go through?
(alternative)

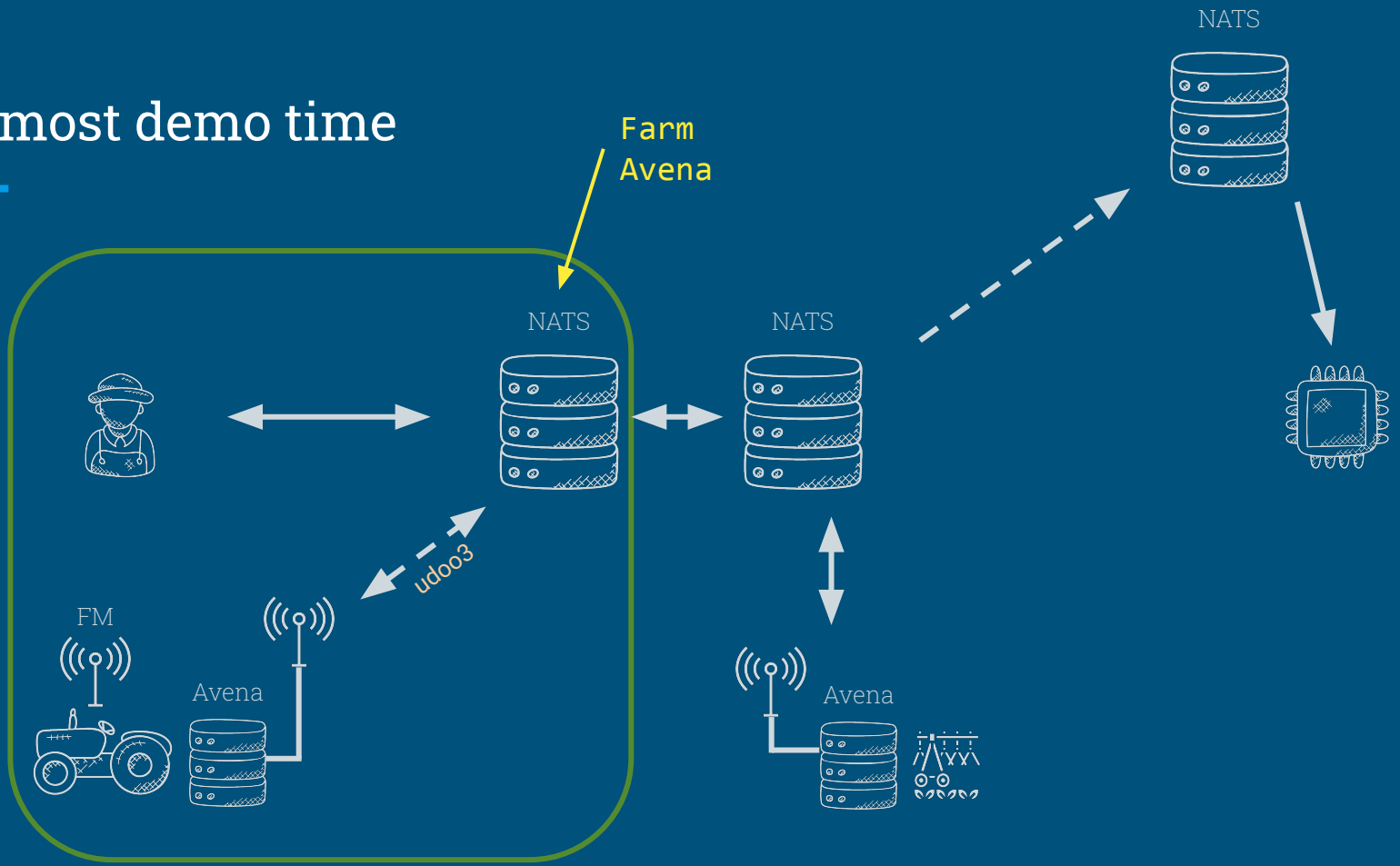
Relay message to seed tender, seed tender physically moves message to the field, and uses the "local voice" network.

More effective routing algorithm.

Ag is a distributed system

Always has been.
Always will be (probably).

Almost demo time



DEMO: ISOBlue and Avena in action

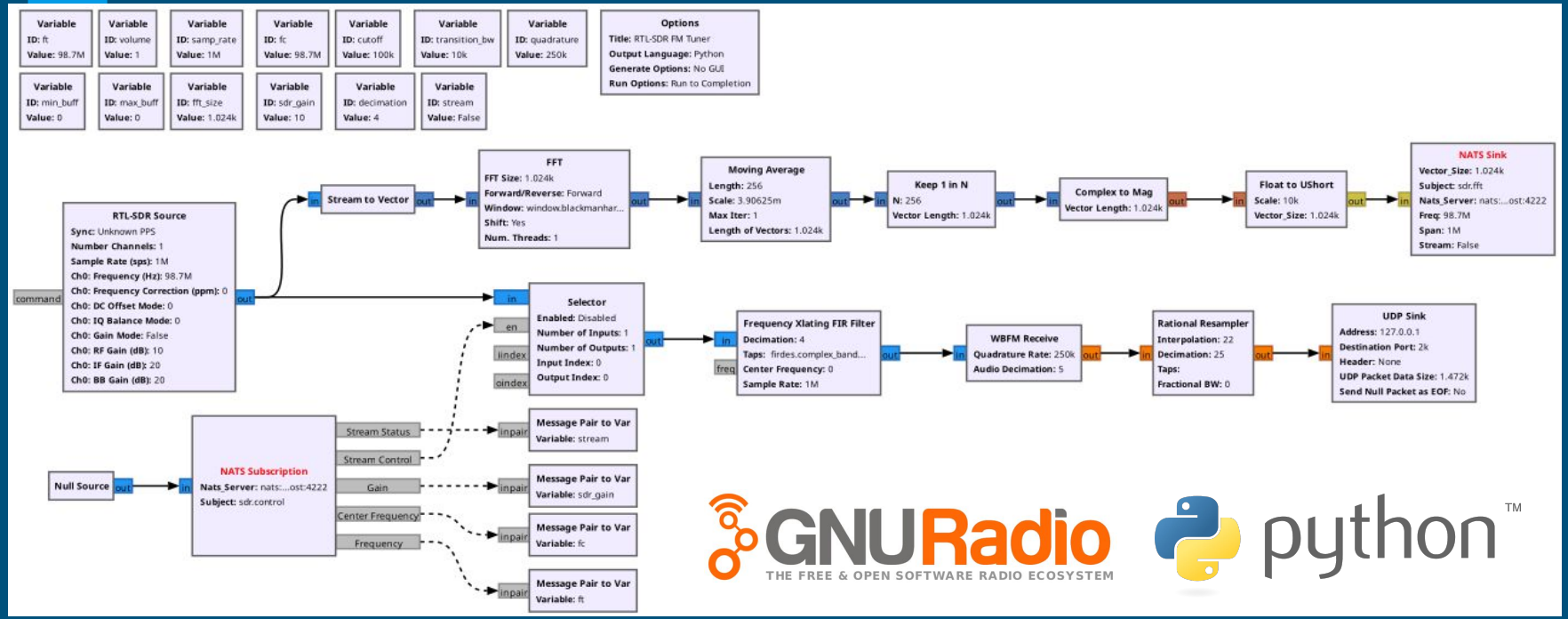
Scan me!

Go to:
avena.oatscenter.org

Open Source:
github.com/oats-center/avena-app

Password:
iot4ag

Only need to add your code... or blocks!



Only need to add your code... or blocks!

```python
from gnuradio import analog
from gnuradio import blocks
from gnuradio import fft
from gnuradio.fft import window
from gnuradio import filter
from gnuradio.filter import firdes
from gnuradio import gr
import sys
import signal
from argparse import ArgumentParser
from gnuradio.eng_arg import eng_float, intx
from gnuradio import eng_notation
from gnuradio import network
import avena_fm_demo_epy_block_0 as epy_block_0  # embedded python block
import avena_fm_demo_epy_block_1 as epy_block_1  # embedded python block
import avena_fm_demo_epy_block_3 as epy_block_3  # embedded python block
import osmosdr
import time



class avena_fm_demo(gr.top_block):

    def __init__(self):
        gr.top_block.__init__(self, "RTL-SDR FM Tuner", catch_exceptions=True)

        ##################################################
        # Variables
        ##################################################
        self.samp_rate = samp_rate = 1e06
        self.volume = volume = 1
        self.transition_bw = transition_bw = 10e3
        self.stream = stream = False
        self.sdr_gain = sdr_gain = 10
        self.quadrature = quadrature = samp_rate/4
        self.min_buff = min_buff = 0
        self.max_buff = max_buff = 0
        self.ft = ft = 98.7e06
        self.fft_size = fft_size = 1024
        self.fc = fc = 98.7e06
        self.decimation = decimation = 4
        self.cutoff = cutoff = 100000.0
        self.audio_rate = audio_rate = 44000
```

```python
import os
import numpy as np
from gnuradio import gr
from pynats2 import NATSClient
import json
from base64 import b64encode, b64decode

class NumpyEncoder(json.JSONEncoder):
    def default(self, obj):
        if isinstance(obj, np.ndarray):
            return obj.tolist()
        return json.JSONEncoder.default(self, obj)

class blk(gr.sync_block):  # other base classes are basic_block, decim_block, interp_block


    def __init__(self, vector_size=1024, subject='fft',
                 nats_server='nats://localhost:4222',
                 freq=98700000, span=2000000, stream=False, gain=0):  # only default arguments here

        gr.sync_block.__init__(
            self,
            name='NATS Sink',   # will show up in GRC
            in_sig=[(np.ushort, vector_size)],
            out_sig=None
        )

        avena_prefix = os.getenv('AVENA_PREFIX')
        self.vector_size = vector_size
        self.freq = freq
        self.span = span
        self.stream = stream
        self.gain = gain
        self.subject = subject
        #self.subject = avena_prefix + '.' + subject
        self.nc = NATSClient(nats_server, socket_timeout=2)
        self.nc.connect()

    def work(self, input_items, output_items):

        b64encpayload = str(b64encode(input_items[0][0]), 'utf-8')
        json_dump = json.dumps({'fft': b64encpayload,
                                'fc' : self.freq,
                                'gain' : self.gain,
                                'span' : self.span,
                                'fft_size' : self.vector_size,
                                'stream' : self.stream},
                                cls=NumpyEncoder)
        self.nc.publish(subject=self.subject ,payload=json_dump)

        return len(input_items[0])
```

Python code generated from GNURadio Companion

Controlled Data Streaming

RTP

SDR FM tuner at ISOBlue

WebRTC Multimedia gateway
in the cloud (server at Purdue)